INDEX

adjoint; 64
asymptotic state observer; 89
asymptotic state reconstructor; 89
auto-correlation function; 47
BIBO; 14; 72
BIBO stability; 49
black box; 107
black box model; 14; 97
block diagram; 4
    algebra; 4
block diagram algebra; 21
Bode; 147
Bode diagram; 139
changing parameters; 10
characteristic polynomial; 65
    closed loop dynamics; 72
closed loop
    control activity function; 72
closed loop
    complementary sensitivity function; 72
    input disturbances - output; 72
    sensitivity function; 71
    unitary feedback equivalent function; 72
closed loop activity function
    performances; 114
continuous process; 6
control
    cascade compensator; 70
    feedback; 17
    feedback from outputs; 215
    feedforward; 162
    LQG; 217
    one degree of freedom; 70
    output estimation; 202
    sampled data; 6
    two degree of freedom; 79
    with total information; 201
control activity; 76
controllability; 13
controllability; 84
conversion
    digital to analogue; 27
converter
    analogue to digital; 27
    digital to analogue; 27
convolution integral; 49
cross-over frequency; 141
detectable; 89
detectable system; 16
determinant; 64
difference dynamics operator; 11
digital control; 6
digital filter; 41
diophantine equation; 74
direct disturbance compensation; 16
disturbance
    additive; 10; 24
    parametric; 10; 24
dual operator; 58
duality; 58; 70
dynamic system
    discrete time; 29
error signal
    system-model; 11
extended system; 12; 108
feedback
    tachometric; 266
feedback loop; 18
feedforward; 162
Fourier transform; 47

function
of interpolation; 28
of reconstruction; 28
gain
at steady state; 66
of acceleration; 66
of acceleration; 67
of speed; 66; 67
steady state; 66; 67
gain margin; 150
gramian
observability; 202
of controllability; 51
gramiano
of observability; 51
guardian filters; 175
Hardy; 44
Hardy spaces; 44
Horowitz; 153
index of non-linearity; 25; 79
lag compensation; 175
lead compensation; 175
LFT; 110
linear fractional transformation; 110
linearisation; 3
loop function; 71
loop gain; 71
loop return function; 71
loop shaping; 137
Lyapunov equation; 51
matrix
conditioning index; 60
structured; 128
trace; 44
maximum absolute value; 45
maximum modulus
theorem; 46
MIMO; 63
model
black box; 10
transparent box; 10
model reference; 15
Nichols chart; 151
non-linearity; 77
norm
of an operator; 49
of signals; 43
notch filter; 175; 184
Nyquist criterion; 142
Nyquist diagram; 138
objective; 13
observability; 89
observability; 13
operator
delay; 22
integrator; 22
summation; 23
operators; 4
overshot; 163
pair of dominant poles; 159
parasitic dynamics; 116
Parseval; 44
Parseval theorem; 44
partial state; 69; 82
performances; 12
phase margin; 149
polar plot; 138
pole; 66
polynomial
monic form; 66
power
of a signal; 47
power spectra; 47
pulse response; 49
pulse sampler; 30
reconstruction function
impulse of Dirac; 28
rectangle; 28
relative sensitivity; 76
resonance peak; 164
resonance peak; 149
robust performance; 123
robust stability; 119
robust stability; 118
robustness; 110
sampling period; 6; 28
sampling pulsation; 32
sensitivity; 75
sensitivity function
performance; 112

separation; 88
settling time; 178
signal
    energy; 44
    input; 6
    output; 6
    reconstructed; 27
    reference; 12
signal reconstruction; 27
signals; 4
singular value; 46; 54
    structured; 126
singular values; 60
SISO; 63
small gain theorem; 119
specifications
    control activity; 198
    measurement noise; 198
    multiplicative plant uncertainty; 199
    reference model; 199
    sensitivity to output disturbances; 197
stabilisability; 84
stabilisable system; 16
stability
    comprehensive; 215
    comprehensive; 251
    essential; 251
    external; 72
    internal; 73
    robust; 12
stability margins; 145
state estimator; 14
state observer; 14
state representation
    canonical form; 68
state variable representation; 1
system
    multivariable; 63
    non-linear; 3
    single input single output; 63
t.f.; 64
theorem
    maximum modulus; 46
    of the separation; 217
time
    delay; 163
    raising; 163
    settling; 163
transfer function; 1
transfer function; 64
transfer function; 8; 24
transfer function frequency band; 164
transfer function matrices; 67
transform
    Fourier; 47
transparent box; 107
transpose operator; 58
type of the control loop; 160
uncertainty; 1
    additive; 116
    additive form
        at denominator; 117
    multiplicative; 115
    multiplicative form
        at denominator; 117
    structured; 125
zero; 66
zero-pole cancellation in the right half plane; 73